

# DEGENERATE STOCHASTIC DIFFERENTIAL EQUATIONS, FLOWS AND HYPOELLIPTICITY\*

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## 1. Introduction.

In this article we shall study stochastic hereditary systems on  $\mathbf{R}^d$ , their flows and regularity of their solutions with respect to  $d$ -dimensional Lebesgue measure. More specifically we will state and outline the proofs of several results on the following issues:

I) Existence of smooth densities for solutions of stochastic hereditary equations whose covariances degenerate polynomially (anywhere) on hypersurfaces in  $\mathbf{R}^d$ .

II) Existence of smooth densities for diffusions with degeneracies of infinite order on a collection of hypersurfaces in  $\mathbf{R}^d$ .

III) Extension and refinement of Hörmander's hypoellipticity theorem for a large class of highly degenerate second order parabolic operators: Hörmander's Lie algebra condition is allowed to fail exponentially fast on the degeneracy hypersurfaces, which are imbedded in submanifolds of dimension less than  $d$ . The exponential decay rate near the degeneracy surface is found to be *optimal*.

Our proofs are based on the Malliavin calculus and require new sharp estimates for Itô processes in Euclidean space.

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## 2. Degenerate SDE's.

We shall consider stochastic differential equations (SDE's) on  $\mathbf{R}^d$  driven by  $n$ -dimensional Brownian motion  $W := (W_1, \dots, W_n)$ , with coefficients that may or may not depend on the history of the solution  $x(t) \in \mathbf{R}^d$ . More specifically we look at the following two types of SDE's:

*Stochastic Hereditary Equations (SHE):*

$$\left. \begin{aligned} dx(t) &= G_0(x_t)dt + \sum_{i=1}^n g_i(x(t-r)) dW_i(t), \quad 0 \leq t \leq a \\ x(t) &= \eta(t), \quad -r \leq t \leq 0. \end{aligned} \right\} \quad (SHE)$$

where  $x_t(s) := x(t+s)$ ,  $-r \leq s \leq 0$ ,  $t \geq 0$ , the segment of  $x$  on  $[t-r, t]$ .

*Stochastic ODE's (SODE's, no memory):*

$$\left. \begin{aligned} dx(t) &= g_0(x(t))dt + \sum_{i=1}^n g_i(x(t)) \circ dW_i(t), \quad 0 < t < a \\ x(0) &= x_0 \in \mathbf{R}^d, \end{aligned} \right\} \quad (SODE)$$

Both (SHE) and (SODE) are defined on the canonical complete filtered Wiener space  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$ , where

$\Omega$  is the space of all continuous paths  $w : \mathbf{R}^+ \rightarrow \mathbf{R}^n$ ,  $w(0) = 0$ , in Euclidean space  $\mathbf{R}^n$ , with compact open topology;

$\mathcal{F}$  is the completed Borel  $\sigma$ -field of  $\Omega$ ;

$P$  is Wiener measure on  $\Omega$ ;

$dW_i(t)$  and  $\circ dW_i(t)$  denote Itô and Stratonovich stochastic differentials respectively;

$r$  is a positive real;

$C := C([-r, 0], \mathbf{R}^d)$  is the Banach space of all continuous paths  $\eta : [-r, 0] \rightarrow \mathbf{R}^d$  on  $d$ -dimensional Euclidean space  $\mathbf{R}^d$ , with sup norm

$$\|\eta\|_\infty := \sup_{-r \leq s \leq 0} |\eta(s)|;$$

and  $|\cdot|$  is the Euclidean norm on  $\mathbf{R}^d$ .

The following conditions will be required:

*Smoothness conditions:*

(S<sub>1</sub>)  $G_0 : C \rightarrow \mathbf{R}^d$  is a continuous map such that at each  $\eta \in C$  it possesses Fréchet derivatives  $D^{(k)}G_0(\eta)$  for all  $k \geq 1$ , which are globally bounded in  $\eta \in C$ .

(S<sub>2</sub>)  $g := (g_1, \dots, g_n) : \mathbf{R}^d \rightarrow \mathbf{R}^{d \times n}$  is  $C^\infty$  and bounded into the space  $\mathbf{R}^{d \times n}$  of  $d \times n$  matrices with the Euclidean norm. All derivatives  $D^{(k)}g_i(v)$ ,  $k \geq 1, 1 \leq i \leq n$ , are globally bounded in  $v \in \mathbf{R}^d$ .

(S<sub>3</sub>)  $g_0 : \mathbf{R}^d \rightarrow \mathbf{R}^d$  is  $C^\infty$  and bounded with all derivatives  $D^{(k)}g_0(v)$ ,  $k \geq 1$ , globally bounded in  $v \in \mathbf{R}^d$ .

*Polynomial Degeneracy Condition:*

(PD) Suppose there is a  $C^2$  real-valued function  $\phi : \mathbf{R}^d \rightarrow \mathbf{R}$ , positive reals  $a, b$  and a neighborhood  $U$  of the surface  $\phi^{-1}(0)$  such that

(i)  $|\nabla\phi(v)| \geq b$  for all  $v \in U$ ;

(ii)

$$g(v)g(v)^* \geq \begin{cases} \alpha I, & \text{if } v \notin U \\ |\phi(v)|^{2p} I, & \text{if } v \in U. \end{cases}$$

Note that condition (PD)'(ii) above implies that

(ii)'  $v \in \phi^{-1}(0)$  whenever  $\hat{g}(v) := \inf\{|g(v)^*(e)| : e \in \mathbf{R}^d, |e| = 1\} = 0$ .

Under Conditions (S<sub>1</sub>) and (S<sub>2</sub>) it is known that the stochastic hereditary equation (SHE) has a unique pathwise solution  $x \in \mathcal{L}^2(\Omega, C([-r, a], \mathbf{R}^d))$  with initial path  $\eta \in C([-r, 0], \mathbf{R}^d)$ , (cf. Mohammed [Mo], 1984, pp. 36-39 and pp. 151-152, Kusuoka and Stroock [K-S]).

Our first result is as follows.

**Theorem 1.**

Assume (PD) for some  $p \geq 1$ , and the smoothness conditions  $(S_1)$ ,  $(S_2)$ . Suppose that the initial path  $\eta \in C([-r, 0], \mathbf{R}^d)$  satisfies

$$\int_{s_1}^{s_2} [\phi(\eta(s))]^2 ds > 0,$$

for every  $s_1, s_2 \in [-r, 0]$  such that  $s_1 < s_2$ . Then, for each  $0 < t \leq a$ , the random variable  $x(t)$  has a distribution which is absolutely continuous with respect to  $d$ -dimensional Lebesgue measure and has a  $C^\infty$  density.

Theorem 1 also holds when the drift  $G_0$  is allowed to be depend on time and on the *whole* history  $x|[-r, t]$ . Using similar techniques to the ones outlined below one can also treat the case of a finite number of *moving degeneracy points*  $v_i(t) \in \mathbf{R}^d$  of polynomial order. ([B-M], 1993).

Although the trajectory  $x_t, t \geq 0$ , gives a Feller process on  $C$ , (SHE) *never admits a stochastic flow on  $C$  when  $r$  is positive*; e.g. for  $H \equiv 0$ ,  $n = d = 1, g = \text{identity}$ , the trajectory of (SHE) has no Borel measurable version  $X : \mathbf{R}^+ \times \Omega \times C \rightarrow C$  with the property that  $X(t, \omega, \cdot) : C \rightarrow C$  is continuous or even locally bounded or linear ([Mo 1-2], 1984, 1986). This pathology poses difficulties in the computation of the Malliavin covariance matrix for the solution  $x(t)$  of (SHE). By contrast, the diffusion equation (SODE) has a smooth flow of diffeomorphisms on  $\mathbf{R}^d$ . This flow is used to compute the necessary lower bounds on the covariance matrix for (SODE) in highly degenerate cases.

**3. Diffusions with Exponential Degeneracies.**

In (SODE) we impose the smoothness conditions  $(S_2)$ ,  $(S_3)$ . In what follows we shall describe the type of degeneracy of infinite order under which the solution  $x(t)$  of (SODE) admits a smooth density with respect to Lebesgue measure on  $\mathbf{R}^d$ .

For any positive integer  $m$ , let  $G^{(m)}$  be the matrix with columns consisting of

$$g_1; \cdots; g_n;$$

together with all vector fields of the form

$$[g_{i_1}, g_{i_2}]_{i_1, i_2=0}^n; \cdots; [g_{i_1}, [g_{i_2}, [g_{i_3}, \cdots, [g_{i_{m-1}}, g_{i_m}]] \cdots]]_{i_1, i_2, \dots, i_m=0}^n,$$

arranged in any specified order. The symbol  $[\cdot, \cdot]$  denotes the Lie bracket operation on smooth vector fields on  $\mathbf{R}^d$ .

Define  $\lambda^{(m)}(x)$  to be the smallest eigenvalue of  $G^{(m)}(x)G^{(m)*}(x)$  for each  $x \in \mathbf{R}^d$ . Clearly  $\lambda^{(m)}(x)$  is independent of the specific ordering of the columns above. Furthermore  $\lambda^{(m)}(x) > 0$  for some  $m \geq 1$  if and only if the parabolic operator  $\frac{1}{2} \sum_{i=1}^n g_i^2 + g_0 + \frac{\partial}{\partial t}$  satisfies Hörmander's general Lie algebra condition at  $(t, x)$  for some  $t > 0$  (and hence for every  $t \in R$ ).

**Definition.**

A point  $x \in \mathbf{R}^d$  is said to be a *Hörmander point* for the diffusion (SODE) if there is an integer  $m \geq 1$  such that  $\lambda^{(m)}(x) > 0$ . Otherwise  $x$  is called a *non-Hörmander point*.

Note that the set  $H$  of all Hörmander points is open in  $\mathbf{R}^d$ . Its compliment  $H^c$  is the set of non-Hörmander points and is closed in  $\mathbf{R}^d$ . It is *not* a smooth submanifold of  $\mathbf{R}^d$ . It may have corners.

We can now state the following

*Exponential Degeneracy Condition (ED)(p):*

For a given point  $x \in \mathbf{R}^d$  suppose there exists  $m \geq 1$ , an open neighborhood  $U$  of  $x$ , a  $C^2$  function  $\phi : U \rightarrow \mathbf{R}$ , and an exponent  $p \in (-1, 0)$  such that

- (i)  $\phi(x) = 0$  and  $\nabla\phi(x) \cdot g_i(x) \neq 0$ , for at least one  $i = 1, \dots, n$ ,
- (ii)  $\lambda^{(m)}(y) \geq \exp(-|\phi(y)|^p)$ , for all  $y \in U$ .

Under the above exponential degeneracy condition we have the following theorem:

**Theorem 2.**

In (SODE) assume the smoothness conditions  $(S_2)$ ,  $(S_3)$  and suppose that for each non-Hörmander point  $x \in \mathbf{R}^d$  there exists  $p \in (-1, 0)$  such that the exponential degeneracy condition  $(ED)(p)$  holds. Then, for each  $t > 0$ , the diffusion  $x(t)$  has a distribution which is absolutely continuous with respect to  $d$ -dimensional Lebesgue measure and has a  $C^\infty$  density.

**4. Hörmander's Theorem for Infinitely Degenerate Parabolic PDE's.**

Consider the second-order partial differential operator

$$L := \frac{1}{2} \sum_{i=1}^n g_i^2 + g_0 + c.$$

where  $c : \mathbf{R}^d \rightarrow \mathbf{R}$  is a smooth bounded function with all derivatives globally bounded.

Define  $G^{(m)}, \lambda^{(m)}$  as in Section 3.

Let  $Lie(g_0, g_1, \dots, g_n)$  be the Lie algebra generated by the vector fields  $g_0, g_1, \dots, g_n$ . By Hörmander's theorem ([H], Theorem 1.1),  $L$  is hypoelliptic on  $\mathbf{R}^d$  if  $Lie(g_0, g_1, \dots, g_n)(x)$  is  $d$ -dimensional for every  $x \in \mathbf{R}^d$ . This condition characterizes hypoellipticity for  $L$  when its coefficients are real analytic. Such a characterization is not valid if the coefficients of  $L$  are smooth but *not analytic*. In fact we have the following example due to Kusuoka and Stroock:

**Example ([K-S]):**

Consider the differential operator

$$L_\sigma := \frac{\partial^2}{\partial x_1^2} + \sigma^2(x_1) \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2}$$

where  $\sigma$  is a  $C^\infty$  real-valued even function, non-decreasing on  $[0, \infty)$ , and vanishing (only) at zero. Then  $L_\sigma$  is hypoelliptic on  $\mathbf{R}^3$  if and only if  $\lim_{x \rightarrow 0^+} x \log \sigma(x) = 0$  ([K-S], Theorem

8.41). E.g.  $L_\sigma$  with  $\sigma(x) = \exp(-|x|^p)$  is hypoelliptic if  $p \in (-1, 0)$ . Hörmander's condition fails for this operator on the hyperplane  $x_1 = 0$ .

Our objective in this section is to establish a criterion for parabolic hypoellipticity of the operator  $L$  sharper than that of Hörmander, in the case where  $L$  has smooth (but not analytic) coefficients. We obtain hypoellipticity of the parabolic operator  $L + \frac{\partial}{\partial t}$  on  $\mathbf{R}^{d+1}$  (and hence of  $L$  on  $\mathbf{R}^d$ ) under hypotheses that allow Hörmander's general condition for the parabolic operator to *fail at an exponential rate* on a collection of surfaces in  $\mathbf{R}^d$ .

**Theorem 3.**

*Let  $D$  be an open set in  $\mathbf{R}^d$ . For the operator  $L$  assume the smoothness conditions  $(S_2)$ ,  $(S_3)$  and suppose that for every non-Hörmander point  $x \in D$  there is a  $p \in (-1, 0)$  such that the exponential degeneracy condition  $(ED)(p)$  holds. Then the differential operator  $L + \frac{\partial}{\partial t}$  is hypoelliptic on  $\mathbf{R} \times D$ .*

**Remarks:**

(i) Assume that the non-Hörmander set  $H^c \cap D$  is imbedded as a closed subset of a  $C^2$  submanifold in  $D$  of dimension less than  $d$ . Suppose further that at every point in  $H^c \cap D$ , at least one of the vector fields  $X_1, \dots, X_n$  is non-tangential to the submanifold. Then the transversality Condition  $(ED)(p)(i)$  is satisfied.

(ii) In the Kusuoka-Stroock example

$$L' := \frac{\partial^2}{\partial x_1^2} + \exp\left\{-\frac{1}{|x_1|}\right\} \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2},$$

the operator  $L'$  is *not hypoelliptic* on  $\mathbf{R}^3$ . Since hypoellipticity of  $L' + \frac{\partial}{\partial t}$  on  $\mathbf{R}^4$  implies hypoellipticity of  $L'$  on  $\mathbf{R}^3$ , then the lower bound  $-1$  on  $p$  in condition  $ED(p)$  is *optimal*.

(iii) Oleinik and Radekevich ([O-R], Theorem 2.5.3, cf. [O]) have shown that if the non-Hörmander set  $H^c$  of  $L$  is compact and  $L$  satisfies condition  $(ED)(p)(i)$  at

all points of  $H^c$ , then  $L$  is hypoelliptic. The above counterexample shows that if the compactness assumption on  $H^c$  is dropped, then a further hypothesis such as (ED)(p)(ii) is required which controls the rate at which the Hörmander condition fails as one approaches the non-Hörmander set.

- (iv) The following alternative form of Theorem 3 shows that the non-vanishing condition in (ED)(p) can be weakened, provided that the range of  $p$  is restricted appropriately. In the statement of the Theorem 4 below, denote the action of the vector field  $g_i$  on a given  $C^\infty$  real-valued function  $\phi$  by  $g_i\phi$  for  $1 \leq i \leq n$ , and the action of the operator  $L-c$  by  $g_{n+1}\phi$ . In this case, we have no reason to believe that the required lower bound,  $-\frac{2}{(18)^r}$ , on  $p$  is optimal for any value of  $r > 1$ !

**Theorem 4.**

*The conclusion of Theorem 3 holds if condition (ED)(p) is replaced by the following:*

*(ED)'(p) There exists an integer  $r \geq 1$ , an open neighborhood  $U \subseteq D$  of  $x$ , a  $C^\infty$  function  $\phi : U \rightarrow \mathbf{R}$ , and an exponent  $p \in (-\frac{2}{(18)^r}, 0)$  such that*

*(i)  $\phi(x) = 0$ , and there exist  $1 \leq i_1, i_2, \dots, i_r \leq n + 1$  such that*

$$g_{i_1}g_{i_2} \cdots g_{i_r}\phi(x) \neq 0.$$

*(ii)  $\lambda^{(m)}(y) \geq \exp(-|\phi(y)|^p)$ , for all  $y \in U$ .*

**4. Outlines of Proofs.**

Here we will only give broad outlines of the proofs of Theorems 1-3. Complete details can be found in ([B-M 1-2]). The proofs use the Malliavin calculus [Ma] together with some precise probabilistic lower bounds for degenerate Itô processes. See Lemmas 1 and 2 below.

*Proof of Theorem 1*

In the following steps we outline a proof of Theorem 1. For further details the reader may refer to ([B-M 2]).

*Step 1:*

We use piecewise linear approximations of  $W$  in (SHE) to compute the Malliavin covariance matrix  $C(T)$  of  $x(T)$  as

$$C(T) = \int_0^T Z(u)g(u, x(u-r))g(u, x(u-r))^* Z(u)^* du,$$

where the  $d \times d$  matrix-valued process  $Z : [0, T] \times \Omega \rightarrow \mathbf{R}^{d \times d}$  satisfies the advanced *anticipating* Stratonovich integral equation

$$\begin{aligned} Z(t) = I + \int_{T \wedge (t+r)}^T Z(u)Dg(x(u-r))(\cdot) \circ dW(u) \\ + \int_t^T Z(u)[\{D_{(2)}G_0(u, x)^*(\cdot)\}'(t)]^* du, \quad 0 \leq t \leq T. \end{aligned}$$

In the above integral equation,  $D_{(2)}G_0(u, x)$  is the Fréchet partial derivative of the map

$$(u, x) \rightarrow G_0(x_u)$$

with respect to  $x \in C([-r, u], \mathbf{R}^d)$ ; and  $D_{(2)}G_0(u, x)^*$  denotes the adjoint of the map  $D_{(2)}G_0(u, x)$  considered as a linear operator from the Cameron Martin subspace of  $C([-r, u], \mathbf{R}^d)$ , into  $\mathbf{R}^d$ .

We solve the above integral equation as follows.

Start with the terminal condition  $Z(T) = I$ . On the last delay period  $[(T-r) \vee 0, T]$  define  $Z$  to be the unique solution of the integral equation

$$Z(t) = I + \int_t^T Z(u)[\{D_{(2)}H(u, x)^*(\cdot)\}'(t)]^* du$$

for a.e.  $t \in ((T-r) \vee 0, T)$ . When  $T > r$ , use successive approximations to solve the anticipating integral equation, treating the stochastic integral as a predefined random *forcing term*. This gives a unique solution of the integral equation by successive backward steps of length  $r$ . Observe that the matrix  $Z(t)$  need not be invertible for small  $t$ . It is interesting to compare  $Z(t)$  with the analogous process for the diffusion case (SODE), (cf.

Step 1 in the proof of Theorems 2 and 3 below). The latter process is invertible *for all times* and its definition *does not* require anticipating stochastic integrals.

*Step 2:*

Since  $D_{(2)}G_0(u, x)$  is globally bounded, then so is  $[D_{(2)}G_0(u, x)^*(\cdot)]'(t)$  in  $(u, x, t)$ . Hence we can choose a *deterministic* time  $t_0 < T$  sufficiently close to  $T$  such that almost surely  $Z(t)$  is invertible and  $\|Z(t)^{-1}\| \leq 2$  for a.e.  $t \in (t_0, T]$ .

*Step 3:*

The above lower bound on  $\|Z(t)\|$  and the representation of  $C(T)$  imply that

$$\det C(T) \geq \frac{1}{4} \int_{t_0}^T \hat{g}(x(u-r))^2 du \quad \text{a.s.}$$

Recall that

$$\hat{g}(v) := \inf\{|g(v)^*(e)| : e \in \mathbf{R}^d, |e| = 1\},$$

for all  $v \in \mathbf{R}^d$ .

*Step 4:*

In view of the polynomial degeneracy condition (PD), we prove the *Propagation*

*Lemma:*

Let  $-r < a < b < a + r$ . Then the statement

$$P\left(\int_a^b |\phi(x(u))|^2 du < \epsilon\right) = o(\epsilon^k)$$

as  $\epsilon \rightarrow 0+$  for every  $k \geq 1$ ,

implies that

$$P\left(\int_{a+r}^{b+r} |\phi(x(u))|^2 du < \epsilon\right) = o(\epsilon^k)$$

as  $\epsilon \rightarrow 0+$  for every  $k \geq 1$ .

*Step 5:*

By successively applying Step 4, we propagate the hypothesis on the initial path  $\eta$  in order to get the estimate:

$$P\left(\int_{t_0}^T |\phi(x(u-r))|^2 du < \epsilon\right) = o(\epsilon^k)$$

as  $\epsilon \rightarrow 0+$  for every  $k \geq 1$ .

*Step 6:*

Using hypothesis (PD), Step 5, Jensen's inequality, and Lemma 3 of [B-M 3], we obtain

$$P\left(\int_{t_0}^T \hat{g}(x(u-r))^2 du < \epsilon\right) = o(\epsilon^k)$$

as  $\epsilon \rightarrow 0+$  for every  $k \geq 1$ .

*Step 7:*

Combining steps 3 and 6 gives

$$P(\det C(T) < \epsilon) = o(\epsilon^k)$$

as  $\epsilon \rightarrow 0+$  for every  $k \geq 1$ . This implies that  $C(T)^{-1}$  exists a.s. and  $\det C(T)^{-1} \in \bigcap_{q=1}^{\infty} \mathcal{L}^q(\Omega, \mathbf{R})$ . The conclusion of Theorem 1 now follows from Malliavin's theorem ([S]).  $\square$

*Proof of Theorem 3*

Let  $x^x$  denote the solution of (SODE) starting at  $x \in \mathbf{R}^d$ ,  $C(t, x)$  the Malliavin covariance matrix of  $x^x(t)$ , and  $\|\cdot\|_q$  the  $\mathcal{L}^q$ -norm on  $\mathcal{L}^q(\Omega, \mathbf{R})$ ,  $q \geq 1$ . Set  $\Delta(t, x) := \det C(t, x)$ . In view of ([K-S], Theorem (8.13)), it is sufficient to verify the following :

For every  $q \geq 1$  and every  $x$  in  $D$ , there exists a neighborhood  $V \subseteq D$  of  $x$  such that

$$\lim_{t \rightarrow 0+} t \log \left\{ \sup_{y \in V} \|\Delta(t, y)^{-1}\|_q \right\} = 0. \quad (\star)$$

In order to verify the above statement we introduce the

**Definition.**

A non-negative random variable  $X$  is said to be *exponentially positive* if there exist positive constants  $c_1$  and  $c_2$  such that

$$P(X < \epsilon) < \exp(-c_1\epsilon^{-1})$$

for all  $\epsilon \in (0, c_2)$ . We call  $c_1$  and  $c_2$  *characteristics* of  $X$ .

Observe that for an Itô process with bounded coefficients, the exit time from a ball is an exponentially positive random variable with characteristics depending only on the bound of the coefficients and the radius of the ball ([I-W], Lemma 10.5, p. 398).

We prove the following two key lemmas:

**Lemma 1.**

Let  $y : [0, T] \times \Omega \rightarrow \mathbf{R}^d$  be the Itô process

$$dy(t) = \sum_{i=1}^n a_i(t) dW_i(t) + b(t) dt, \quad 0 \leq t \leq T,$$

where  $a_1, \dots, a_n, b : [0, T] \times \Omega \rightarrow \mathbf{R}^d$  are measurable  $(\mathcal{F}_t)_{0 \leq t \leq T}$ -adapted processes, all bounded a.s. by a deterministic constant  $c_3$ . Suppose that  $\tau \leq T$  is an exponentially positive  $(\mathcal{F}_t)_{0 \leq t \leq T}$ -stopping time such that at least one diffusion coefficient  $a_i$  satisfies the condition: a.s.,  $|a_i(s)| \geq \delta$ , for all  $0 \leq s \leq \tau$ , for some deterministic  $\delta > 0$ . Then for every  $m \geq 2$ , there exist positive constants  $c_4, c_5$  and  $T_0$  such that for all  $t \in (0, T_0)$  and  $\epsilon \in (0, c_4 t^{m+1})$ , the following holds

$$P\left(\int_0^{t \wedge \tau} |y(u)|^m du < \epsilon\right) < \exp\left\{-c_5 \epsilon^{-\frac{1}{m+1}}\right\}.$$

The constants  $c_4$  and  $c_5$  can be chosen to depend only on  $m, c_3, \delta$ , and the characteristics of  $\tau$ . The constant  $T_0$  depends only on the characteristics of  $\tau$ .

The second key lemma is a version of the composition lemma under the exponential degeneracy hypothesis (ED)(p).

**Lemma 2.**

Let  $\tau$  be an exponentially positive  $(\mathcal{F}_t)_{0 \leq t \leq T}$ -stopping time and let  $p \in (-1, 0)$ .

Suppose  $y$  is an Itô process with a.s bounded coefficients, and suppose further that  $y$  and  $\tau$  satisfy the last estimate in Lemma 1 for some  $m > -\frac{p}{p+1}$ . Then there exist positive constants  $T_1, c_6, c_7$  and  $q > 1$  such that for all  $t \in (0, T_1)$  and all  $\epsilon < \exp\{-c_6 t^{-\frac{1}{q}}\}$ , the following holds

$$P\left(\int_0^{t \wedge \tau} \exp(-|y(u)|^p) du < \epsilon\right) < \exp\{-c_7 |\log \epsilon|^q\}.$$

Furthermore, the constants  $T_1, c_6, c_7$  and  $q$  are completely determined by  $c_3, c_4, c_5$  in Lemma 1,  $p, m$  and the characteristics of  $\tau$ .

Proofs of Lemmas 1 and 2 are given in [B-M 1].

In the following steps we verify the Kusuoka-Stroock condition  $(\star)$ .

*Step 1*

The Malliavin covariance is given by

$$C(t, x) = Y^x(t) \int_0^t Z^x(s) g(x^x(s)) g(x^x(s))^* Z^x(s)^* ds [Y^x(t)]^*.$$

where  $Y^x(t)$  is the derivative of the stochastic flow  $x \rightarrow x^x(t, \omega)$  on  $\mathbf{R}^d$  with respect to  $x$  for a.a.  $\omega \in \Omega$ , and  $Z^x(t) := Y^x(t)^{-1}$ .

These matrix-valued processes satisfy the integral equations

$$Y^x(t) = I + \sum_{i=1}^n \int_0^t Dg_i(x^x(s)) Y^x(s) \circ dW_i(s) + \int_0^t Dg_0(x^x(s)) Y^x(s) ds,$$

and

$$Z^x(t) = I - \sum_{i=1}^n \int_0^t Z^x(s) Dg_i(x^x(s)) \circ dW_i(s) - \int_0^t Z^x(s) Dg_0(x^x(s)) ds.$$

See ([K-S], p.3-4), ([B], p.75).

*Step 2*

We obtain the following estimate by an elementary argument:

For every  $q \geq 1$  and every bounded set  $V \subset \mathbf{R}^d$  there exists a positive constant  $c_8$  such that for all  $t \in (0, T)$  and  $x \in V$ , we have

$$\|\Delta(t, x)^{-1}\|_{2q}^{2q} \leq c_8 \left\{ 1 + \sum_{j=1}^{\infty} P\left(Q(t, x) < j^{-\frac{1}{2dq}}\right) \right\},$$

where

$$Q(t, x) := \inf \left\{ \sum_{i=1}^n \int_0^t \langle Z^x(u) g_i(x^x(u)), h \rangle^2 du : h \in \mathbf{R}^d, |h| = 1 \right\}.$$

Let  $m \geq 1$ ,  $x_0 \in \mathbf{R}^d$ ,  $t \in (0, T)$  and let  $x$  belong to a fixed bounded neighborhood  $W$  of  $x_0$ . Define

$$\tau_1 := \inf \left\{ s > 0 : |x^x(s) - x| \vee \|Z^x(s) - I\| = \frac{1}{2} \right\} \wedge T.$$

Then (cf. [K-S], 1985) there exist positive constants  $c_9, c_{10}$  and exponents  $r_1, r_2 \in (0, 1)$  such that for all  $t \in (0, T)$ ,  $x \in W$ , and  $\epsilon \in (0, c_9)$ , the following inequality holds :

$$\begin{aligned} P(Q(t, x) < \epsilon) &\leq \exp(-c_{10}\epsilon^{-r_1}) + \\ &+ \epsilon^{-d} \sup \left\{ P\left(\sum_{j=1}^N \int_0^{t \wedge \tau_1} \langle Z^x(u) K_j(x^x(u)), h \rangle^2 du < \epsilon^{r_2}\right) : |h| = 1 \right\} \end{aligned}$$

where the vector fields  $K_1, \dots, K_N$  are the columns of the matrix function  $G^{(m)}$ .

*Step 3*

From the definition of  $\tau_1$  and Step 2 we get

$$P(Q(t, x) < \epsilon) \leq \exp(-c_{10}\epsilon^{-r_1}) + \epsilon^{-d} P\left(\int_0^{t \wedge \tau_1} \lambda^{(m)}(x^x(u)) du < \epsilon^{r_2}\right).$$

*Step 4*

Suppose  $x_0$  is a Hörmander point. Then for some  $m \geq 1$ ,  $\lambda^{(m)}$  is bounded away from zero by some  $\delta > 0$  in a neighborhood  $V$  of  $x_0$ . This fact and Step 3 imply that

$$P(Q(t, x) < \epsilon) \leq c_{11} \exp(-c_{12}\epsilon^{-c_{13}r_3})$$

provided  $t > \frac{\epsilon^{r_2}}{\delta}$ , where  $r_3 := r_1 \wedge r_2$ ;  $c_{11}$ ,  $c_{12}$  and  $c_{13}$  are positive constants, independent of  $(t, x) \in (0, T) \times V$ .

*Step 5*

By Steps 2 and 4,

$$\|\Delta(t, x)^{-1}\|_{2q}^{2q} \leq c_8 \left\{ (\delta t)^{-\frac{2dq}{r_2}} + A(t) \right\},$$

where

$$\begin{aligned} A(t) &:= 1 + \sum_{j=k}^{\infty} c_{11} \exp(-c_{12}j^{r_4}), \\ &\leq 1 + \sum_{j=1}^{\infty} c_{11} \exp(-c_{12}j^{r_4}) < \infty, \end{aligned}$$

$r_4 := \frac{c_{13}r_3}{2dq} > 0$ , and  $k := [(\delta t)^{-\frac{2dq}{r_2}}]$  is the integer part of  $(\delta t)^{-\frac{2dq}{r_2}}$ . Thus  $\|\Delta(t, x)^{-1}\|_q$  may not explode faster than *algebraically* as  $t \downarrow 0$ , *locally uniformly* with respect to  $x$  near  $x_0$ . Hence the Kusuoka-Stroock condition  $(\star)$  holds.

*Step 6*

Let  $x_0$  be a non-Hörmander point. By Itô's formula

$$d\phi(x^x(t)) = \sum_{i=1}^n \nabla\phi(x^x(t)) \cdot g_i(x^x(t)) dW_i(t) + (L - c)\phi(x^x(t)) dt.$$

for  $x$  near  $x_0$ . The transversality condition in (ED)(p) implies that the process  $\phi(x^x(t))$  satisfies the hypotheses of Lemma 1. Applying Lemma 1 and 2, we deduce the existence

of an exponentially positive stopping time  $\tau_3$  and positive constants  $c_6, c_7, T_1$  and  $q' > 1$ , all independent of  $x$  near  $x_0$  such that for all  $t \in (0, T_1)$  and  $\epsilon < \exp(-c_6 t^{-\frac{1}{q'}})$

$$P\left(\int_0^{t \wedge \tau_1 \wedge \tau_3} \exp(-|\phi(x^x(u))|^p) du < \epsilon\right) < \exp\{-c_7 |\log \epsilon|^{q'}\}.$$

*Step 7*

The estimates in Steps 3 and 6, and the condition (ED)(p) yield

$$P(Q(t, x) < \epsilon) \leq \exp(-c_{10} \epsilon^{-r_1}) + \epsilon^{-d} \exp(-c_7 |\log \epsilon^{r_2}|^{q'})$$

for  $t \in (0, T_1)$  and  $\epsilon < \exp(-c_6 t^{-\frac{1}{q'}})$ .

*Step 8*

Combining Step 7 with the first estimate in Step 2 gives

$$\|\Delta(t, x)^{-1}\|_{2q}^{2q} \leq c_8 \left\{ \exp(2dq c_6 t^{-\frac{1}{q'}}) + c_{14} \right\}, \quad 0 < t < T_1$$

where

$$c_{14} := 1 + \sum_{j=1}^{\infty} \left\{ \exp\left(-c_{10} j^{\frac{r_1}{2dq}}\right) + j^{1/2q} \exp(-c_7 |\log j^{-\frac{r_2}{2dq}}|^{q'}) \right\} < \infty.$$

Note that the constants  $c_6, c_8$  and  $c_{14}$  can all be chosen to be independent of  $x$  in a neighborhood of  $x_0$ . Hence  $\|\Delta(t, x)^{-1}\|_q$  may not explode faster than *exponentially* as  $t \downarrow 0$ . Because  $q' > 1$ , the Kusuoka-Stroock condition  $(\star)$  is also satisfied in this case. Thus the operator  $L$  is parabolic hypoelliptic.  $\square$

Theorem 2 follows immediately from  $(\star)$  and Theorem (3.17) in ([K-S]).

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